

Motivation

- Gaussian filters are commonly used to improve signal to noise ratio (SNR) of PET images but reduces spatial resolution, thus increases partial volume effects.
- The edge preserving *bilateral filter* (BF) is able to overcome these shortcomings [1] but requires manual tuning of two free parameters σ_S and σ_I :

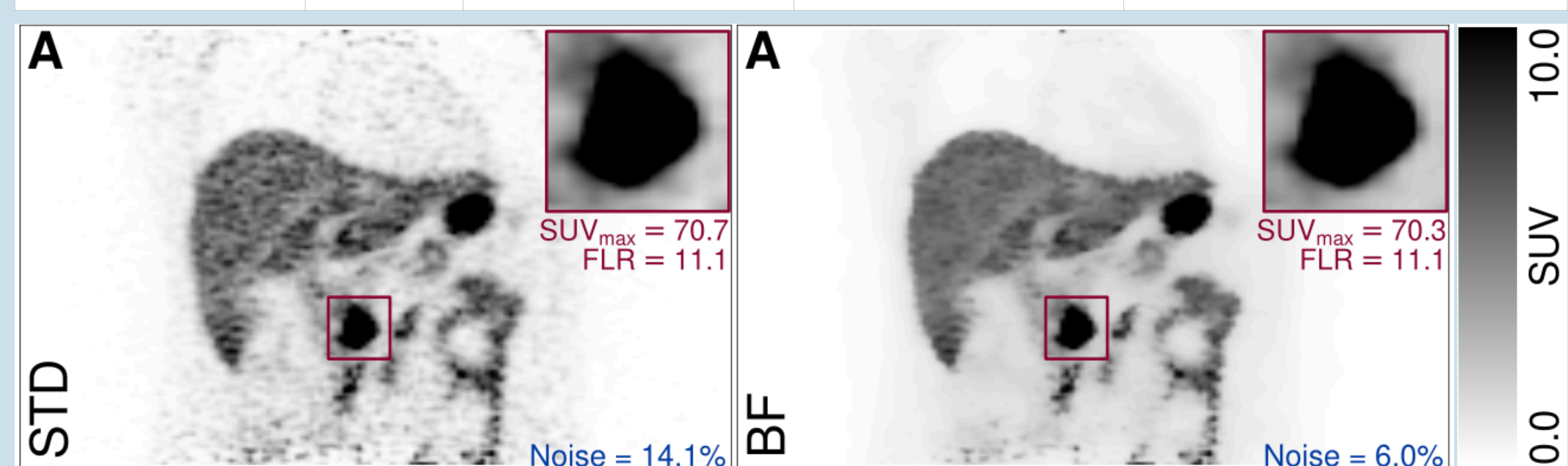
$$W(m, n) = \underbrace{\exp \left[-\frac{(\vec{P}_m - \vec{P}_n)^2}{2\sigma_S^2} \right]}_{\text{spatial domain } (W_S)} \cdot \underbrace{\exp \left[-\frac{(I_m - I_n)^2}{2\sigma_I^2} \right]}_{\text{intensity domain } (W_I)}$$

- ➔ This is time consuming and hampers clinical use despite attractive filtering properties.
- ➔ Development of a method for automatic filter parameter optimization.

Results

- For 19/69 datasets our method required manual parameter tuning (due to over-smoothed background or visible artefacts).
- Optimal parameter values varied over a substantial range (mean \pm SD: $\sigma_I = (1.4 \pm 1.5)$ SUV and $\sigma_S = (5.5 \pm 1.7)$ mm)
- σ_I exhibits a pronounced tracer dependance (cf. figure)
- ΔSUV_{max} of the focal uptake ROIs across all datasets was small (-0.5 ± 0.8) while substantial noise reduction was achieved by ΔNoise (-12.3 ± 3.5) percentage points, although behaviour differed between tracers.

	[¹⁸ F]-FDG	[¹⁸ F]-LDOPA	[⁶⁸ Ga]-DOTATATE	All
ΔSUV_{max} [g/mL]	-0.33 ± 0.31	-0.26 ± 0.20	-1.63 ± 1.30	-0.51 ± 0.75
ΔNoise [pp]	-12.7 ± 2.9	-13.0 ± 3.3	-9.6 ± 4.3	-12.3 ± 3.5

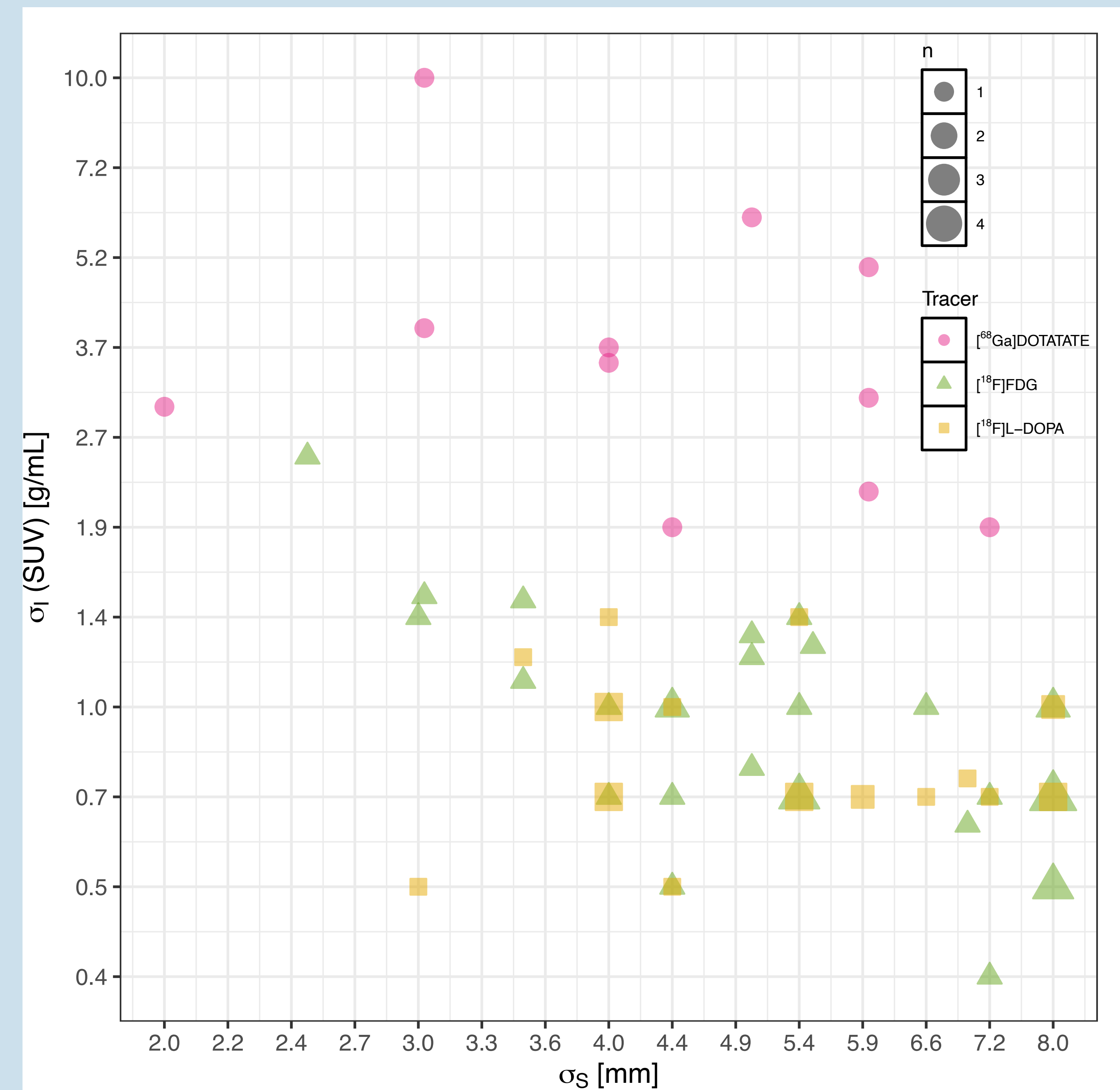


Methods

- 552 low SNR image volumes from 69 clinical respiratory-gated PET/CT measurements (8 gates), three different tracer entities: [¹⁸F]-FDG (N=33), [¹⁸F]-LDOPA (N=25), [⁶⁸Ga]-DOTATATE (N=11).
- Delineated four 3D ROIs: one within liver (to assess noise), three in areas with elevated focal uptake (e.g. lesions).
- Generated 225 differently BF-filtered versions of each volume (sum: 124200) by varying σ_S and σ_I based on a 15x15 grid covering a logarithmic range from 2 mm to 8 mm for σ_S and from 0.1 to 10.0 SUV for σ_I .
- Optimization of σ_S and σ_I via objective function S :

$$S(\sigma_S, \sigma_I) = \sum_{i=1}^g \sum_{j=1}^l \left[\Delta\text{SUV}_{max}^{i,j}(\sigma_S, \sigma_I) \right]^2 + \sum_{i=1}^g \left[\Delta\text{Noise}^i(\sigma_S, \sigma_I) \right]^2$$

with $\Delta\text{SUV}_{max}^{i,j}$ and ΔNoise^i as the fractional differences between original (STD) and BF-processed gate-specific SUV_{max} and noise level.



Conclusions

- Results demonstrate inter-individual and tracer-specific variability of optimal BF parameters
 - ➔ Underlines the need for careful parameter optimization.
- In 72% of all cases our automated method was able to perform parameter optimization without any user intervention.
 - ➔ More work needed to further improve the success rate.
- ➔ Our method already reduces workload when considering BF for routine use.

[1] F. Hofheinz, et al. Suitability of bilateral filtering for edge-preserving noise reduction in PET. EJNMMI Research 2011 1:23, doi: [10.1186/2191-219X-1-23](https://doi.org/10.1186/2191-219X-1-23)